

Probabilistically Checkable Proofs

Computability & Complexity

May 24, 2019

Definition (NP)

A language $L \in NP$ iff there exists a TM P (verifier), that reads the input string x and a proof string π such that:

- **Completeness** : $x \in L \implies \exists \pi V(x, \pi) = 1$
- **Soundness** : $x \notin L \implies \forall \pi V(x, \pi) = 0$

Examples:

- 3-SAT
- 3-colorable graphs

What happens if we limit the verifier but allow mistakes?

Definition (PCP)

A language $L \in PCP(r, q)$ iff there exists a TM P (verifier), that reads the input string x , r random bits and q bits from a proof string π such that:

- **Completeness** : $x \in L \implies \exists \pi Pr_r[V(x, \pi) = 1] = 1$
- **Soundness** : $x \in L \implies \forall \pi Pr_r[V(x, \pi) = 0] > 1/2$

Examples:

- 3-SAT instances where either all or less than half clauses can be satisfied
- 3-colorable graphs where either all or less than half edges can be bicolor

i.e : constraint satisfaction is either perfect or very bad

Known Classes In The PCP Format

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$$PCP[\log(n), O(1)] = ?$$

Known Classes In The PCP Format

Theorem

$$PCP[\log(n), O(1)] \subset NP$$

Proof.

We must show that for every $PCP[\log(n), O(1)]$ verifier there is an NP verifier. For every random string of bits it can read $O(1)$ bits, so in all possible runs it can read at most $2^{\log(n)} * O(1)$ bits. We can make an NP verifier that reads all possible inputs of the PCP verifier as the proof. \square

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Why wouldn't $PCP[poly(n), O(1)] \in NP$ work? Because the verifier can read too much and the equivalent input would be exponential. In fact $PCP[poly(n), O(1)] = NEXP$

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What about the reverse?

Classical PCP Theorem

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$NP \subseteq PCP[\log(n), O(1)]$

This means that every NP problem has a probabilistic checking scheme. i.e we can demand the proof in specific format (PCP format) such that the mistake can be found everywhere.

Initial Proof



PCP transformation



PCP format



Another View of PCP

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To get a assignment in PCP format we would need to force the problem to be only able to be either 100% satisfied or at most 50% satisfied.

Another View of PCP

Definition (q-CSP)

A q-CSP problem is a set of m q-ary constraints. It is a YES instance when there exists an assignment that satisfies all of them and NO otherwise.

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Theorem (Equivalent of PCP theorem)

There exist ρ and q such that ρ -Gap-q-CSP is NP-hard.

This shows the hardness of approximation connection!

Theorem

The two statements are equivalent:

- *There exist ρ and q such that ρ -Gap- q -CSP is NP-hard.*
- $NP \subseteq PCP(\log(n), O(1))$

Proof.

- (\rightarrow) Any NP problem can be reduced to the ρ -Gap- q -CSP which will either be satisfied or at most ρ constraints are satisfied. The PCP samples a constraint to check.
- (\leftarrow) We make 1 constraint for each run of the PCP verifier. The constraint is true if the verifier accepts. Hence at most ρ clauses are satisfied if its a NO instance.



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1st proof by Arora et al (1998).

2nd proof by Dinur (2007) using expander graphs. 2019 Goedel Prize.

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$$UNSAT(G) \geq 1/|E|.$$

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By applying this transformation $\log(E)$ times we obtain a graph with constant $UNSAT$, i.e we robustify it.

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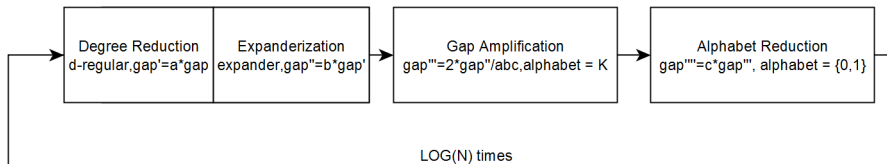
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Theorem (DIN07)

There exists Σ_0 such that the following holds. For any finite alphabet Σ there exist $C > 0$ and $0 < a < 1$ such that, given a constraint graph $G = \langle (V, E), \Sigma, C \rangle$, one can construct in polynomial time, a constraint graph $G' = \langle (V', E'), \Sigma_0, C' \rangle$ such that

- $\text{size}(G) < C * \text{size}(G')$
- $\text{UNSAT}(G) = 0 \implies \text{UNSAT}(G') = 0$
- $\text{UNSAT}(G') \geq \min(2 * \text{UNSAT}(G), a)$

Background: Expanders

Definition

The edge boundary of a set S , denoted ∂S , is the edges emanating from S , $\partial S = E(S, \bar{S})$. The edge expansion ratio of G , denoted $h(G)$ is

$$h(G) = \min_S \frac{|\partial S|}{|S|}$$

Definition

A d -regular graph with n vertices, $h(G) \geq \eta$ is called an (n, d, η) -expander.

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Such graphs exist. Can we construct them? Yes!

Theorem

There exists η such that for every n, d there is an efficient to construct a (n, d, η) -expander.

Background: Expanders

Intuitively expanders are highly connected graphs, and they have several useful properties.

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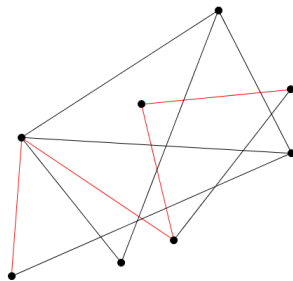
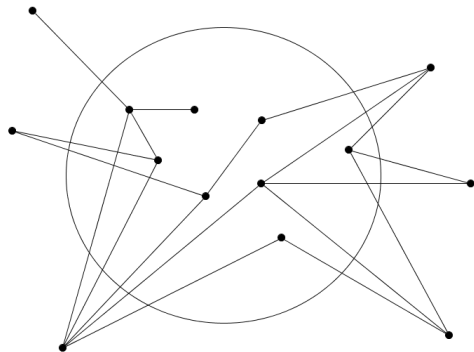
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Theorem

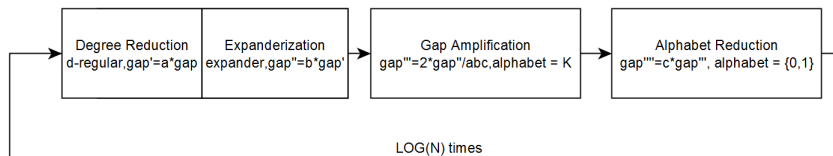
Let $G = (V, E)$ be a d -regular graph with second eigenvalue λ . Let $F \subset E$ be a set of edges without self loop, and let K be the distribution on vertices induced by selecting a random edge in F , and then a random endpoint.

The probability p that a random walk that starts with distribution K takes the $i + 1$ st step in F , is upper bounded by $\frac{|F|}{|E|} + \left(\frac{|\lambda|}{d}\right)^i$.

Background: Expanders



Overview



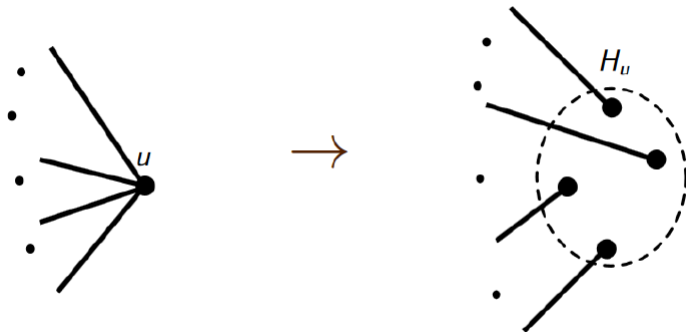
Degree Reduction

Here the graph is made regular without making it too much easier to color.

Vertices are replaced with a $d-1$ -regular expander.

(Papadimitriou-Yannakakis gadget)

After this step UNSAT is increased by a constant.



Expanderization

Here certain edges are added to make the graph an expander.

$$NewGraph = OldGraph \cup Expander$$

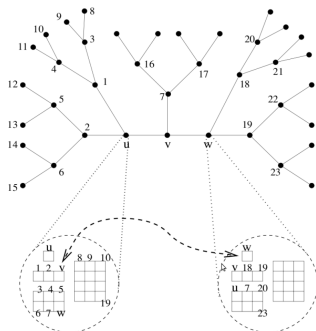
The new edges are null constraints so UNSAT can only increase but only by a constant again.

Gap Amplification

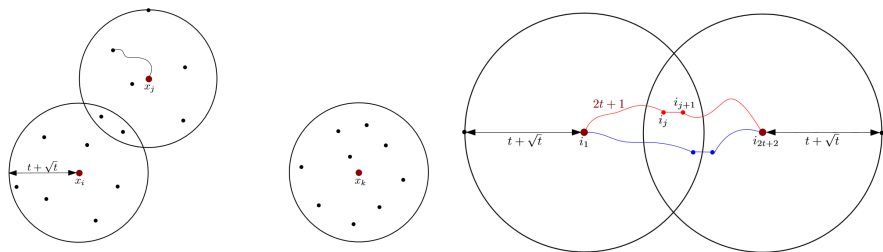
A new graph is constructed such that an edge (constraint) between A, B exists iff there was a walk of length t from A to B .

The alphabet(colors) is now $\{0, 1\}^{dt}$. Every vertex now has "opinion" about every other vertex within distance t from it.

The new constraints are satisfied iff the opinions of A, B agree on common nodes and they satisfy the original constraints.



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Hence approximately $1 - (1 - \frac{|F|}{|E|})^t$ of the new vertices violate their constraints.

Hence $1 - (1 - \frac{|F|}{|E|})^t \approx 1 - (1 - t * \frac{|F|}{|E|}) = t * \frac{|F|}{|E|}$

This means UNSAT is increased by a constant of our choice every time we execute this step!

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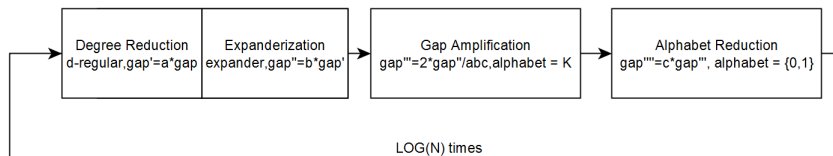
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Tools: Hadamard encoding and Linearity testing

For another time...

Overview



- According to the PCP theorem we can spread a "mistake" all over the proof.
- It is equivalent to "robustifying" an NP-hard problem.
- To do that Dinur defines a transformation applied $\text{Log}(n)$ times that each time doubles the area of the mistake.
- Central to Dinur's proof are expander graphs that permit distributing the mistake everywhere through small walks.



Irit Dinur

The PCP Theorem by Gap Amplification

<http://www.wisdom.weizmann.ac.il/~dinuri/mypapers/combpcp.pdf>



Jaikumar Radhakrishnan, and Madhu Sudan

On Dinurs Proof of the PCP Theorem

people.csail.mit.edu/dmoshkov/courses/pcp/dinur_pcp_overview.pdf



S. Arora, and B. Barak

Computational Complexity: A Modern Approach, chapter 18

<https://theory.cs.princeton.edu/complexity/book.pdf>



S. Hoory, N Linial, and A. Wigderson

EXPANDER GRAPHS AND THEIR APPLICATIONS

http://www.cs.huji.ac.il/~nati/PAPERS/expander_survey.pdf