

Hard Instances of Lattice Problems

Average Case - Worst Case Connections

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Outline

Abstract

Lattices

The Random Class

Worst-Case - Average-Case Connection

Abstract

Hard Problems Already Exist

All Time Classic Hard Problems

- ▶ NP-Complete problems
- ▶ Factorization
- ▶ Discrete Logarithm

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Worst-Case Hardness

Those problems are hard only under certain distributions. Often it is not clear how to find such a distribution.

One Step Further

Worst-Case Vs. Average-Case Hardness

A random class of lattices so that if the SVP is *easy* to solve then the above problems are easy in every lattice.

Lattices

Lattice Definition

Definition

Let $B \in \mathbb{R}^{m \times n}$, we consider the set $\mathcal{L} = \{y : y = B \cdot x \quad \forall x \in \mathbb{Z}^{1 \times n}\}$, that is the set of all integer linear combinations of B . We call every \mathcal{L} with the above properties a lattice.

Lattices

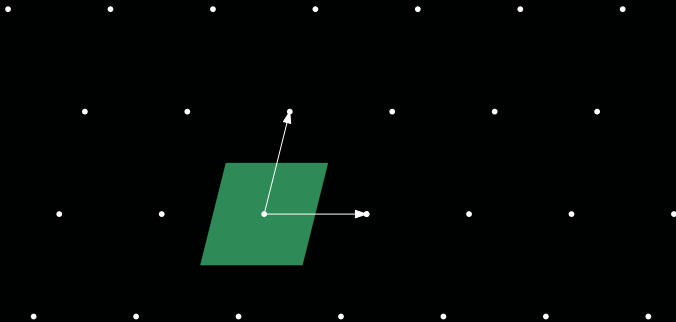


Figure: An example of a lattice and its basis.

Lattices

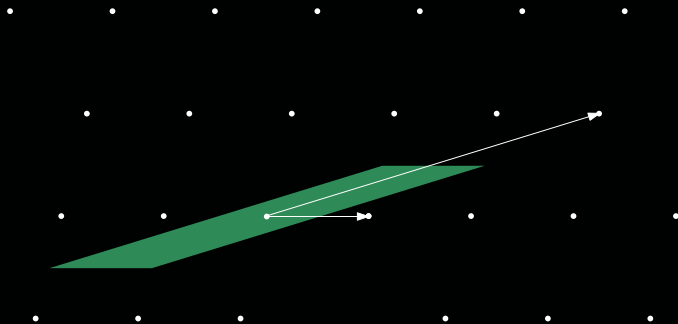


Figure: A lattice has more than one bases.

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- ▶ Multiplication by a unimodular matrix produces a new basis.
- ▶ Infinite (countable) different bases.
- ▶ The only part of a lattice that is known is the place where the basis vectors lie.

Fundamental Parallelepiped

Definition

Let \mathcal{L} be a lattice, and let a basis for \mathcal{L} is $B = [b_1, \dots, b_n]$, b_i are the column vectors of B , then we define the set

$\mathcal{P}(B) = \{y : y = \sum_{i=1}^n x_i \cdot b_i, \quad x_i \in [-\frac{1}{2}, \frac{1}{2})\}$. We call $\mathcal{P}(B)$ the fundamental parallelepiped of \mathcal{L} with respect to the basis B .

Mathematical Tools

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- ▶ Efficiently computable distinguished representatives as $t - B \cdot \lceil B^{-1} \cdot t \rceil$.
- ▶ Partition of the space \mathbb{R}^n by multiples of fundamental parallelepiped.

Lattice Problems & Solutions

Classic Hard Problems

P1 approximate SVP

P2 approximate unique SVP

P3 approximate SIVP (find a basis)

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Classic Algorithms and Bounds

- ▶ LLL Reduction Algorithm ($2^{\frac{n-1}{2}}$ $sh(\mathcal{L})$ approximation).
- ▶ Babai's Nearest Plane Algorithm.

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Bounds

- ▶ Shor proved that in LLL the approximation factor can be replaced by $(1 + \epsilon)^n$.
- ▶ Minkowski (Convex Body Theorems) $sh(\mathcal{L}) \leq c\sqrt{n} \det(\mathcal{L})^{\frac{1}{n}}$

More on Lattices...

Definition (Dual Lattice)

Let \mathcal{L} be a lattice, we define the dual lattice to be the set $\mathcal{L}^ = \{y : \forall x \in \mathcal{L} \langle x, y \rangle \in \mathbb{Z}\}$.*

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Definition (Smoothing Parameter)

For any n -dimensional lattice \mathcal{L} and $\epsilon \in \mathbb{R}^+$, we define its smoothing parameter $\eta_\epsilon(\mathcal{L})$ to be the smallest s such that $\rho_{1/s}(\mathcal{L}^* \setminus \{0\}) \leq \epsilon$.

Sampling

Lemma

For any $s > 0$, $c \in \mathbb{R}^n$ and lattice $\mathcal{L}(B)$, the statistical distance between $D_{s,c} \bmod \mathcal{P}(B)$ and the uniform distribution over $\mathcal{P}(B)$ is at most $\frac{1}{2}\rho_{1/s}(\mathcal{L}(B)^ \setminus \{0\})$. In particular, for any $\epsilon > 0$ and any $s \geq \eta_\epsilon(B)$, holds that*

$$\Delta(D_{s,c} \bmod \mathcal{P}(B), U(\mathcal{P}(B))) \leq \epsilon/2$$

The Random Class

Definition of \mathcal{L} and Λ

1. \mathcal{L} : q -ary lattice.
2. Λ : the perpendicular lattice of \mathcal{L} .

Definition of \mathcal{L} and Λ

Symbols

- ▶ $B = (u_1 : u_2 : \dots : u_m)$, $u_i \in \mathbb{Z}^n$.
- ▶ Lattice: $\mathcal{L}(B, q) = \{y : y = B \cdot x \pmod{q}, \forall x \in \mathbb{Z}^{1 \times m}\}$
($\mathcal{L}(B, q) \subseteq \mathbb{Z}^n$).
- ▶ Perpendicular Lattice: $\Lambda(B, q) = \{y : y \cdot B \equiv \mathbf{0} \pmod{q}\}$
($\Lambda(B, q) \subseteq \mathbb{Z}^n$).

Parameters

- ▶ $m = \lceil c_1 n \log n \rceil$
- ▶ $q = \lceil n^{c_2} \rceil$

Our Goal

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1. Redefine the basis B so that if there is a PT algorithm that finds a shortest vector in Λ then it breaks P1, P2, P3 in any lattice.

First Step

Substitute B by λ'

Define $\lambda' = (v_1, \dots, v_m)$, $v_i \in \mathbb{Z}_q^n$. Every v_i is chosen independently and with uniform distribution from the set of all vectors in \mathbb{Z}_q^n .

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Simultaneous Diophantine Equations

The problem of finding a SV in $\Lambda(\lambda', q)$ is equivalent to solve a linear simultaneous Diophantine equation.

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Theorem (Dirichlet)

If c_1 is sufficiently large with respect to c_2 then there is always a SV in $\Lambda(\lambda', q)$ which is sorter than n .

Problem :-(

$\Lambda(\lambda', q)$ is Unknown to Everybody (Crypto Only)

It seems that there is no way of constructing a shortest vector in $\Lambda(\lambda', q)$. So we don't have a trapdoor!

Second Step

Substitute λ' by λ

Define $\lambda = (v_1, \dots, v_m)$, $\forall i \in \{1, \dots, m-1\} v_i \in \mathbb{Z}_q^n$ also v_i is chosen independently and with uniform distribution from the set of all vectors in \mathbb{Z}_q^n . We also define $v_m = -\sum_{i=1}^{m-1} \delta_i v_i$. Where δ_i is a, randomly generated, sequence of 0 and 1's.

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No Loss of Generality

The distribution of λ is exponentially close to the uniform distribution. $\sum_{x \in A} \left| P(\lambda = x) - \frac{1}{|A|} \right| \leq \frac{1}{2^{cn}}$, where A is the set of all possible values of λ .

Worst-Case - Average-Case Connection

Main Theorem

Theorem

There are absolute constants c_1, c_2, c_3 so that the following holds:

Suppose that there is a PPT algorithm \mathcal{A} which given a value of the random variable λ_{n,c_1,c_2} as an input, with a probability of at least $\frac{1}{2}$ outputs a nonzero vector of $\Lambda(\lambda_{n,c_1,c_2}, [n^{c_1}])$ of length at most n .

*Then, there is a PPT algorithm \mathcal{B} with the following properties:
If the linearly independent vectors $a_1, \dots, a_n \in \mathbb{Z}^n$ are given as an input then in polynomial time in $\sum \text{size}(a_i)$ gives the output (d_1, \dots, d_n) so that with probability of greater than $1 - \frac{1}{2^{-\sum \text{size}(a_i)}}$
 (d_1, \dots, d_n) is a basis with $\max \|d_i\| \leq n^{c_3} \text{bl}(\mathcal{L})$*

Main Tool for the Proof

Easy Construction of a Basis

There is a polynomial time algorithm that from a set of n linearly independent vectors $r_1, \dots, r_n \in \mathcal{L}$ can construct a basis s_1, \dots, s_n of \mathcal{L} so that $\max \|s_i\| \leq n \max \|r_i\|$

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Defining a new Goal

Construct a set of n linearly independent vectors of \mathcal{L} so that each of them is shorter than $n^{c_3-1} bl(\mathcal{L})$.

Proof of Main Theorem

Assume that we have the set of linearly independent vectors $a_1, \dots, a_n \in \mathcal{L}$. Let $M = \max \|a_i\|$

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First Case (Trivial)

If $M \leq n^{c_3-1} bl(\mathcal{L})$ we are done.

Proof of Main Theorem

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First Case (Trivial)

If $M \leq n^{c_3-1} bl(\mathcal{L})$ we are done.

Second Case (Hmmm...)

If $M > n^{c_3-1} bl(\mathcal{L})$ we construct (?) a set of linearly independent vectors of $b_1, \dots, b_n \in \mathcal{L}$ so that $\max \|b_i\| \leq \frac{M}{2}$. Then we repeat the algorithm with input the set b_1, \dots, b_n .



After $\log_2 M \leq 2 \sum size(a_i)$ steps we get a set of linearly independent vectors where each of them is shorter than $n^{c_3-1} bl(\mathcal{L})$.

$$\max \|b_j\| \leq \frac{M}{2}$$




1. Starting from the set $a_1, \dots, a_n \in \mathcal{L}$ we construct a set of linearly independent vectors $f_1, \dots, f_n \in \mathcal{L}$ so that $\max \|f_j\| \leq n^3 M$ and also the parallelepiped $W = \mathcal{P}(f_1, \dots, f_n)$ is very close to a cube.
2. We cut W into q^n parallelepipeds each of the form $\sum \frac{t_i}{q} f_i + \frac{1}{q} W$, where $0 \leq t_i < q$ is a sequence of integers.
3. We take a random sequence of lattice points ξ_1, \dots, ξ_m , $m = \lfloor c_1 n \log n \rfloor$ from W . Let $\xi_j \in \sum \frac{t_i^{(j)}}{q} f_i + \frac{1}{q} W$ then we define $v_j = (t_1^{(j)}, \dots, t_n^{(j)})$.
4. Apply \mathcal{A} to the input $\lambda' = (v_1, \dots, v_m)$ and get a vector $(h_1, \dots, h_m) \in \mathbb{Z}^n$.
5. Then the vector $\sum h_j (\xi_j - \eta_j) \in \mathcal{L}$ and its length is at most $\frac{M}{2}$, where $\eta_j = \sum \frac{t_i^{(j)}}{q} f_i$.

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Thank you!!!