Function & Total Search Complexity Classes

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November 29, 2012

## $L \in NP$

There is a polynomial-time decidable, polynomially balanced relation  $R_L$  such that for all strings x: there is a string y with  $R_L(x, y)$  if and only if  $x \in L$ .

#### FL

Given x, find a string y such that  $R_L(x, y)$  if such a string exists; if no such string exists, return "no".

# **Function Problems**

### Reductions

### Functions Problems: $A \leq B$

- if x is an instance of A, then R(x) is an instance of B.
- if there exists a solution for A with input x, then there exists a solution for B with input R(x).
- if z is a solution for R(x), then S(z) is a solution for x.
- ► *R*, *S* are computable in logarithmic space.

#### $FP = FNP \iff P = NP$

- SAT can be solved in polynomial time if and only if FSAT can be solved in polynomial time
- FSAT is FNP-complete

### Function Problem

- Decision Problem: Decide if a solution exists ("yes", "no")
- Search Problem: if "yes", find a solution

### Total Search Problem

A "Total" FNP (TFNP) problem is an FNP problem where a solution is guaranteed to exist.

# **Total Search Problems**

## $FP \subseteq TFNP \subseteq FNP$

#### $\blacktriangleright FP = TFNP \Rightarrow P = NP \cap coNP$

 $\blacktriangleright TFNP = FNP \Rightarrow NP = coNP$ 

Interesting to define classes of problems where solution is guaranteed to exist by a non-constructive proof.

#### Plan

- Represent possible configurations with nodes.
- Find a relation between nodes (Edges). The relation must be chosen so that the solutions are nodes with a special property (The non-consturctive proof helps!)

# **Total Search Problems**

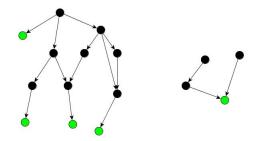
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#### Figure: FIND SINK

#### Argument in Proof of Existence

Every finite directed acyclic graph has a sink.

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## Stable configuration for neural networks

Neural Network:

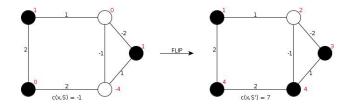
- ► *G* = (*V*, *E*)
- $S: V \rightarrow \{-1, 1\}$  (Nodes)
- ► Stable Configuration:  $(\forall i \in V)S(i) \cdot \sum_{\{i,j\} \in E} S(j)w_{ij} \ge 0$

Define:

• Cost: 
$$c(x, S) = \sum_{\{i,j\}\in E} S(i)S(j)w_{ij}$$

Neigborhood (Edges):

$$S' \in N(x,S) \iff (S' \in FLIP(S) \land (c(x,S') > c(x,S))$$



Stable Configuration for neural networks  $\leq$  FIND SINK

Sinks  $\subseteq$  Solutions: If node *i* is flipped and  $S(i) \cdot \sum_{\{i,j\} \in E} S(j)w_{ij} = -\delta < 0$ , then  $c(x, S') = c(x, S) + 2\delta$ .

## **PLS-complete** Problems

- ► TSP, under the Kernighan-Lin neighborhood.
- MAX-CUT, under the flip neighborhood.
- Stable configuration for neural networks.

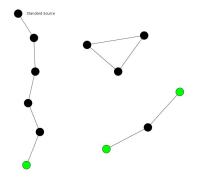


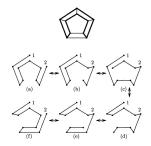
Figure: ODD DEGREE NODE

#### Argument in Proof of Existence

Any finite graph has an even number of odd-degree nodes *OR* All graphs of degree two or less have an even number of leaves.

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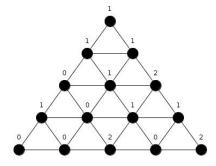


#### SMITH

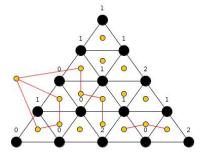
Given a graph G with odd degrees, and a Hamilton cycle, find another one.

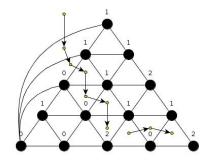
- ▶ Nodes: Hamilton Paths without edge {1,2}.
- ► Edges: Add an edge to the endpoint (≠ 1) and break cycle in a unique way.

# Sperner's Lemma



# Sperner's Lemma





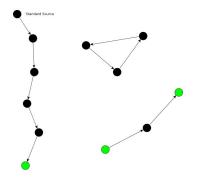


Figure: END OF THE LINE

#### Argument in Proof of Existence

If a finite directed graph has an unbalanced node (a vertex with different in-degree and out-degree), then it has another one.

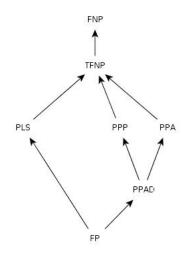
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## PPAD-complete Problems

- 3D SPERNER
- BROUWER
- NASH

# Hierarchy



#### Figure: Search Classes

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