# Probabilistically Checkable Proofs

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## PCP's and Hardness of Approximation

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# 2 PCP's and Hardness of Approximation

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Image: A matrix

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Weird question: Can we do better than that? I mean, can we ignore most part of the proof??

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- We then check randomly a constant number of its bits:
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# The surprising main idea

- In general, a mathematical proof is invalid if it has even a single error somewhere, which can be very difficult to detect.
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**Initial Proof** 



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**Initial Proof** 

**PCP** transformation





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# Towards a new definition of NP

## <u>Note</u>: From now on, we shall refer to languages $L \subseteq \{0,1\}^*$ .

## Definition (NP classic definition)

 $NP = \cup_{k \in \mathbb{N}} NTIME(n^k)$ 

### Definition (*NP* "yes"-certificate definition)

A language *L* is in *NP* if there exists a polynomial  $p : \mathbb{N} \to \mathbb{N}$  and a deterministic polynomial-time TM *M* (called the **verifier** of *L*) such that for every  $x \in \{0, 1\}^*$ ,

$$x \in L \Leftrightarrow \exists u \in \{0,1\}^{p(|x|)}$$
 such that  $M(x,u) = 1$ .

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- Informally, *NP* is the complexity class of problems for which it is easy to check that a solution is correct.
- In contrast, finding solutions to *NP* problems is widely believed to be hard.
- Consider for example the problem 3-SAT. Given a 3-CNF Boolean formula, it is notoriously difficult to come up with a satisfying assignment, whereas given a proposed assignment it is trivial to plug in the values and verify its correctness. Such an assignment is an *NP*-proof for the satisfiability of the formula.

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# Definition (NP alternative definition)

An alternative way to define NP is as the class of all languages  $L \subseteq \{0,1\}^*$  that have **efficient** proof systems: proof systems in which there is a polynomial-time algorithm that verifies correctness of the statement  $x \in L$  with assistance of a proof.

• One problem with the usual proof systems (i.e. the "yes"-certificates for *NP*) is that these proofs are very <u>sensitive to error</u>. A false theorem can be "proven" by a proof that consists of only one erroneous step. Similarly, a 3-SAT formula  $\phi$  can be unsatisfiable, yet have an assignment that satisfies all clauses but one. In these cases, the verifier must check every single proof step / clause in order to make sure that the proof is correct.

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- In contrast, the **PCP theorem** gives each set in *NP* an alternative proof system, in which proofs are robust.
- In this system a proof for a false statement is guaranteed to have many errors.
- As a result, a verifier can randomly read only a few bits from the proof and decide, with *high probability* of success, whether the proof is valid or not.

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## Definition (NP revisited - The NP verifier)

 $L \in NP$  iff there exists a poly-time TM V (the verifier) such that:

$$x \in L \Rightarrow \exists \pi \text{ such that } V^{\pi}(x) = 1,$$
  
 $x \notin L \Rightarrow \forall \pi, \ V^{\pi}(x) = 0.$ 

 $(\pi \text{ is a proof})$ 

### Definition (The PCP verifier)

Let *L* be a language and  $q, r : \mathbb{N} \to \mathbb{N}$ . We say that *L* has an (r(n), q(n))-PCP verifier if there's a polynomial-time probabilistic algorithm *V* satisfying:

- Efficiency: On input x ∈ {0,1}<sup>n</sup> and given random access to a string π ∈ {0,1}\* of length at most q(n)2<sup>r(n)</sup> (the proof), V uses at most r(n) random coins and makes at most q(n) nonadaptive queries to locations of π. Then it outputs "1" (for "accept") or "0" (for "reject"). We let V<sup>π</sup>(x) denote the random variable representing V's output on input x and with random access to π.
- Completeness: x ∈ L ⇒ ∃π ∈ {0,1}\* such that Pr[V<sup>π</sup>(x) = 1] = 1. (We call this string π the correct proof for x.)

• Soundness:  $x \notin L \Rightarrow \forall \pi \in \{0,1\}^*, \Pr[V^{\pi}(x) = 1] \leq 1/2.$ 

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# Theorem (PCP Theorem - Arora, Lund, Motwani, Sudan, Szegedy, Safra)

 $NP = PCP[O(\log n), O(1)].$ 



#### Lemma

## $PCP[O(\log n), O(1)] \subseteq NP.$

#### Proof.

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On board...



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#### Lemma

 $NP \subseteq PCP[O(\log n), O(1)].$ 

We will definitely **not** prove this right now, all we can say is that Dinur's approach is based on finding **gap-introducing** reductions.

#### Theorem

If there is a gap-introducing reduction for some problem L in NP, then  $L \in PCP[O(\log n), O(1)]$ . In particular, if L is NP-complete then the PCP theorem holds.

#### Proof.

Suppose  $L \in NP$ , and there is a reduction to a 3CNF formula  $\phi_x$  with m clauses and with the following properties:

 $x \in L \Rightarrow \phi_x$  is satisfiable

 $x \notin L \Rightarrow$  no assignment satisfies more than  $(1 - \epsilon_1)m$  clauses of  $\phi_x$ .

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# Proof (Continued).

- V picks  $O(\frac{1}{\epsilon_1})$  clauses of  $\phi_x$  at random, and checks if w satisfies them all.
- $O(\frac{1}{\epsilon_1} \log m) = O(\log |x|)$  random bits used.
- Number of bits read by the verifier:  $O(\frac{1}{\epsilon_1}) = O(1)$ .
- $x \in L \Rightarrow \phi_x$  is satisfiable

 $\Rightarrow \exists w \text{ such that } V^w(x) \text{ always accept.}$ 

 $x \notin L \Rightarrow \forall w$  a fraction  $\epsilon_1$  of clauses of  $\phi_x$  are unsatisfied by w $\Rightarrow \forall w \ V^w(x)$  rejects with probability  $\geq \frac{1}{2}$ (the probability that it doesn't reject is  $\leq (1 - \epsilon_1)^{1/\epsilon_1} \leq 1/2$ 

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#### Theorem

The PCP theorem implies that there is an  $\epsilon_1 > 0$  such that there is no polynomial  $(1 - \epsilon_1)$ -approximation algorithm for Max3SAT, unless P = NP.

| Proof.   |  |
|----------|--|
| On board |  |

For every  $\epsilon > 0$ ,  $NP = PCP_{1-\epsilon,\frac{1}{2}+\epsilon}[O(\log n), 3]$ . Furthermore, the verifier behaves as follows: it uses its randomness to pick three entries i, j, k in the proof w and a bit b, and it accepts iff  $w_i \oplus w_j \oplus w_k = b$ .

#### Consequences

- Through a reduction from 3SAT to MaxE3LIN-2, we get that MaxE3LIN-2 cannot be approximated within a factor better than 2, unless *P* = *NP*.
- Furthermore, Max3SAT cannot be approximated withn a factor better than 8/7, unless *P* = *NP*.
- Finally, MaxCUT has an approximability bound of 17/16.

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### Theorem (Guruswami, Lewin, Sudan, Trevisan 98)

$$NP = PCP_{1,\frac{1}{2}+\epsilon}[O(\log n), 3], \ \forall \epsilon > 0$$

Proof of Optimality of the above result

Theorem (Karloff, Zwick 97)  $P = PCP_{1,\frac{1}{2}}[O(\log n), 3]$  Theorem (Guruswami, Lewin, Sudan, Trevisan 98)

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Proof of Optimality of the above result

Theorem (Karloff, Zwick 97)

 $P = PCP_{1,\frac{1}{2}}[O(\log n), 3]$ 

### Problem (Vertex Cover)

Given an undirected graph G = (V, E), a vertex cover is a set  $C \subseteq V$  such that every edge  $(u, v) \in E$  has one endpoint in C. We want to find the Minimum Vertex Cover.

#### Problem (Independent Set)

Given an undirected graph G = (V, E), an independent set is a set  $S \subseteq V$  such that for every  $u, v \in S$  we have  $(u, v) \notin E$ . We want to find the Maximum Independent Set.

- Observe that a set C is a vertex cover iff  $V \setminus C$  is an independent set.
- Thus, the two problems are actually the "same".
- However, in terms of approximability, they are very different.

### Problem (Vertex Cover)

Given an undirected graph G = (V, E), a vertex cover is a set  $C \subseteq V$  such that every edge  $(u, v) \in E$  has one endpoint in C. We want to find the Minimum Vertex Cover.

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Given an undirected graph G = (V, E), an independent set is a set  $S \subseteq V$  such that for every  $u, v \in S$  we have  $(u, v) \notin E$ . We want to find the Maximum Independent Set.

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## Vertex Cover

- A simple algorithm (just find a maximal matching and take both endpoints) gives a 2-approximation for VC.
- It has been proved (Dinur and Safra) that VC is *NP*-hard to approximate within a factor of 1.3606.
- Assuming the Unique Games Conjecture, we get a tight 2 o(1) inapproximability for VC (Khot and Regev).

- Assuming ZPP ≠ NP, for every ε > 0 there is no n<sup>1-ε</sup>-approximation algorithm for Independent Set.
- If a graph G = (V, E) has maximum degree d, then a maximal independent set contains at least |V|/(d+1) vertices, and so is a (d+1)-approximate solution.
- This can be improved to an  $O(d \log \log d / \log d)$ -approximation.
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# THANK YOU!

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