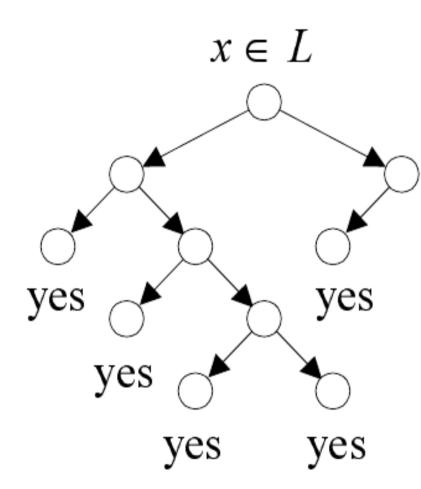
CoNP and Function Problems

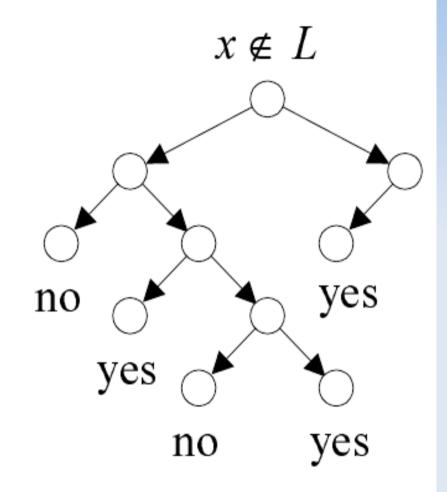
coNP

- By definition, coNP is the class of problems whose complement is in NP.
- NP is the class of problems that have succinct certificates.
- coNP is therefore the class of problems that have succinct disqualifications:
 - A "no" instance of a problem in coNP possesses a short proof of its being a "no" instance.
 - Only "no" instances have such proofs.

coNP (continued)

- Suppose L is a coNP problem.
- There exists a polynomial-time nondeterministic algorithm M such that:
 - If x ∈ L, then M (x) = "yes" for all computation paths.
 - If x ∈ L, then M (x) = "no" for some computation path.





coNP (concluded)

- Clearly $P \subseteq coNP$.
- It is not known if $P = NP \cap coNP$.
 - Contrast this with R = RE ∩ coRE

Some coNP Problems

• VALIDITY \in coNP.

 If φ is not valid, it can be disqualified very succinctly: a truth assignment that does not satisfy it.

• SAT complement \in coNP.

- The disqualification is a truth assignment that satisfies it.
- HAMILTONIAN PATH complement \in coNP.
 - The disqualification is a Hamiltonian path.

An Alternative Characterization of coNP

- Let L ⊆ Σ* be a language. Then L ∈ coNP if and only if there is a polynomially decidable and polynomially balanced relation R such that L = {x : \forall y (x, y) ∈ R}.
- L' = {x : (x, y) $\in R$ for some y}.
- Because _¬ R remains polynomially balanced, L ∈ NP
- Hence $L \in coNP$ by definition.

coNP Completeness

- L is NP-complete if and only if its complement
 L' = Σ* L is coNP-complete.
- Proof (⇒; the ⇐ part is symmetric)
 - Let L1' be any coNP language.
 - Hence $L1 \in NP$.
 - Let R be the reduction from L1 to L.
 - So $x \in L1$ if and only if $R(x) \in L$.
 - So $x \in L1'$ if and only if $R(x) \in L'$.
 - R is a reduction from L1' to L'.

Some coNP-Complete Problems

- SAT complement is coNP-complete.
 - SAT complement is the complement of sat.
- VALIDITY is coNP-complete.
 - φ is valid if and only if $\neg \varphi$ is not satisfiable.
 - The reduction from sat complement to VALIDITY is hence easy.
- HAMILTONIAN PATH complement is coNPcomplete.

Possible Relations between P, NP, coNP

- 1. P = NP = coNP.
- 2. NP = coNP but $P \neq NP$.
- **3**. NP \neq coNP and P \neq NP.
 - This is current "consensus."

coNP Hardness and NP Hardness

- If a coNP-hard problem is in NP, then NP = coNP.
- Let $L \in NP$ be coNP-hard.
- Let PNTM M decide L.
- For any L1 ∈ coNP, there is a reduction R from L1 to L.
- L1 \in NP as it is decided by PNTM M(R(x)).
 - Alternatively, NP is closed under complement.
- Hence $coNP \subseteq NP$.
- The other direction NP \subseteq coNP is symmetric.

coNP Hardness and NP Hardness (concluded)

- Similarly, If an NP-hard problem is in coNP, then NP = coNP.
- Hence NP-complete problems are unlikely to be in coNP and coNP-complete problems are unlikely to be in NP.

The Primality Problem

- An integer p is prime if p > 1 and all positive numbers other than 1 and p itself cannot divide it.
- PRIMES asks if an integer N is a prime number
- Dividing N by 2, 3, . . , \sqrt{N} is not efficient.
 - The length of N is only log N , but $\sqrt{N} = 2^{0.5 \log N}$.
- A polynomial-time algorithm for primes was not found until 2002 by Agrawal, Kayal, and Saxena!
- We will focus on efficient "probabilistic" algorithms for primes (used in practice).

ΔΝΡ

- ΔNP ≡ NP ∩ coNP is the class of problems that have succinct certificates and succinct disqualifications.
 - Each "yes" instance has a succinct certificate.
 - Each "no" instance has a succinct disqualification.
 - No instances have both.
- $P \subseteq \Delta NP$.
- We will see that primes \in DP.
 - In fact, primes \in P as mentioned earlier.

Primitive Roots in Finite Fields

- Theorem (Lucas and Lehmer (1927)) A number
 p > 1 is prime if and only if there is a number
 1<r<p (called the primitive root or generator) s.t.
- I r^{p-1} = 1 mod p, and
- 2. r^{(p-1)/q} = 1 mod p for all prime divisors q of p-1.
- Proof excluded.

Pratt's Theorem

- (Pratt (1975)) PRIMES \in NP \cap coNP.
- primes is in coNP because a succinct disqualification is a divisor.
- Suppose p is a prime.
- p's certificate includes the r in L.L. Theorem
- Use recursive doubling to check if r^{p-1}=1modp in time polynomial in the length of the input, log p.
- We also need all prime divisors of p 1: q1, q2
 , . . , qk .
- Checking $r^{(p-1)/qi} \neq 1 \mod p$ is also easy.

The Proof (concluded)

- Checking q1, q2, ..., qk are all the divisors of p – 1 is easy.
- We still need certificates for the primality of the qi 's.
- The complete certificate is recursive and treelike: C(p) = (r; q1, C(q1), q2, C(q2), ..., qk, C(qk)).
- C(p) can also be checked in polynomial time.
- We next prove that C(p) is succinct.

The Succinctness of the Certificate

- The length of C(p) is at most quadratic at 5 log²p.
- This claim holds when p = 2 or p = 3.
- In general, p 1 has k < log p prime divisors
 q1 = 2, q2, ..., qk.
- C(p) requires: 2 parentheses and 2k < 2 log p separators (length at most 2 log p long), r (length at most log p), q1 = 2 and its certificate 1 (length at most 5 bits), the qi 's (length at most 2 log p), and the C(qi)s.

The Proof (concluded)

 C(p) is succinct because $|C(p)| \le 5 \log p + 5 + 5 \Sigma_{i=2}^{k} \log^2 qi$ $\leq 5 \log p + 5 + 5 (\Sigma_{i=2}^{k} \log 2 qi)^{2}$ $\leq 5 \log p + 5 + 5 \log (p-1)/2$ $< 5 \log p + 5 + 5(\log 2 p - 1)^{2}$ $= 5 \log^2 p + 10 - 5 \log^2 p \le 5 \log^2 p$ for $p \ge 4$.

Function Problems

- Decisions problem are yes/no problems (sat, tsp (d),etc.).
- Function problems require a solution (a satisfying truth assignment, a best tsp tour, etc.).
- Optimization problems are clearly function problems.
- What is the relation between function and decision problems?
- Which one is harder?

Function Problems Cannot Be Easier than Decision Problems

- If we know how to generate a solution, we can solve the corresponding decision problem.
 - If you can find a satisfying truth assignment efficiently, then sat is in P.
 - If you can find the best tsp tour efficiently, then tsp(d) is in P.
- But decision problems can be as hard as thecorresponding function problems.

FSAT

FSAT is this function problem:

- Let $\phi(x1, x2, \ldots, xn)$ be a boolean expression.
- If φ is satisfiable, then return a satisfying truth assignment.
- Otherwise, return "no."
- We next show that if SAT ∈ P, then FSAT has a polynomial-time algorithm.

An Algorithm for FSAT Using SAT

1: t := ε;

2: if $\phi \in SAT$ then

- 3: for i = 1, 2, . . . , n do
- 4: if ϕ [xi = true] \in SAT then
- 5: t := t U { xi = true };
- 6: $\phi := \phi[x_i = true];$
- 7: else
- 8: t := t ∪ { xi = false };
- 9: φ := φ[xi = false];
- 10: end if
- 11: end for
- 12: return t;
- 13: else
- 14: return "no";
- 15: end if

Analysis

- There are \leq n + 1 calls to the algorithm for SAT
- Shorter boolean expressions than φ are used in each call to the algorithm for sat.
- So if SAT can be solved in polynomial time, so can FSAT.
- Hence SAT and FSAT are equally hard (or easy).

TSP and TSP (d) Revisited

- We are given n cities 1, 2, ..., n and integer distances dij = dji between any two cities i and j.
- The TSP asks for a tour with the shortest total distance (not just the shortest total distance, as earlier).
 - The shortest total distance must be at most 2^{|x|} where x is the input.
- TSP (d) asks if there is a tour with a total distance at most B.
- We next show that if TSP (d) ∈ P, then TSP has a polynomial-time algorithm.

An Algorithm for tsp Using tsp (d)

- 1: Perform a binary search over interval [0, 2^{|×|}] by calling tsp (d) to obtain the shortest distance C;
- 2: for i, j = 1, 2, . . . , n do
- 3: Call tsp (d) with B = C and dij = C + 1;
- 4: if "no" then
- 5: Restore dij to old value; {Edge [i, j] is critical.}
- 6: end if
- 7: end for
- 8: return the tour with edges whose dij \leq C;

Analysis

- An edge that is not on any optimal tour will be eliminated, with its dij set to C + 1.
- An edge which is not on all remaining optimal tours will also be eliminated.
- So the algorithm ends with n edges which are not eliminated.
- There are O(| x | + n²) calls to the algorithm for tsp (d).
- So if tsp (d) can be solved in polynomial time, so can tsp.
- Hence tsp (d) and tsp are equally hard (or easy).

FNP and FP

- L € NP iff there exists poly-time computable R_L(x,y) s.t.
 X € L ⇔ y { |y| ≤ p(|x|) & R_L(x,y) }
 - Note how R_L defines the problem-language L
- The corresponding search problem Π_{R(L)} € FNP is: given an x find any y s.t. R_L(x,y) and reply "no" if none exist
 - Are all FNP problems self-reducible like FSAT? [open?]
- FP is the subclass of FNP where we only consider problems for which a poly-time algorithm is known

FP <?> FNP

- A proof a-la-Cook shows that FSAT is FNPcomplete
- Hence, if FSAT∈FP then FNP = FP
- But we showed self-reducibility for SAT, so the theorem follows:
- Theorem: FP = FNP iff P=NP

TFNP

- What happens if the relation R is total?
- i.e., for each x there is at least one y s.t. R(x,y)
- Define TFNP to be the subclass of FNP where the relation R is total
 - TFNP contains problems that always have a solution, e.g. factoring, fix-point theorems, graph-theoretic problems, ...
 - How do we know a solution exists?
 - By an "inefficient proof of existence", i.e. non-(efficiently)-constructive proof
- The idea is to categorize the problems in TFNP based on the type of inefficient argument that guarantees their solution

Properties of TFNP FP ⊆ TFNP ⊆ FNP

- 2. TFNP = $F(NP \cap coNP)$
 - NP = problems with "yes" certificate y s.t. $R_1(x,y)$
 - coNP = problems with "no" certificate z s.t. $R_2(x,y)$
 - for TFNP $F(NP \cap coNP)$ take $R = R_1 U R_2$
 - for $F(NP \cap coNP)$ TFNP take $R_1 = R$ and $R_2 = \emptyset$
- 3. There is an FNP-complete problem in TFNP iff NP = coNP
 - \rightarrow : If NP = coNP then trivially FNP = TFNP
- 4. TFNP is a semantic complexity class → no complete problems!
 - note how telling whether a relation is total is undecidable (and not even RE!!)

ANOTHER HC is in TFNP

- Thm: any graph with odd degrees has an even number of HC through edge xy
- Proof Idea:
 - take a HC
 - remove edge (1,2) & take a HP
 - fix endpoint 1 and start "rotating" from the other end
 - each HP has two "valid" neighbors (d=3) except for those paths with endpoints 1,2

